

Adaptive Quasi-Monte Carlo Integration

June 4th, 2002

Rudolf Schröder

The Problem

Given a function

$$f: C_s \rightarrow \mathbb{R},$$

with $C_s = [0, 1]^s \subset \mathbb{R}^s$ denoting the s -dimensional unit cube.

Calculate an approximation Qf for the multi-variate integral

$$If := \int_{C_s} f(\mathbf{x}) d\mathbf{x}.$$

Qf has to be based on f -evaluations at n points $\mathbf{x}_i \in C_s$ which can be chosen arbitrarily by the integration routine.

Therefore, Qf will be of the form

$$Q_n f = \sum_{i=1}^n w_i f(\mathbf{x}_i).$$

Monte Carlo Integration

$$Q_n f := \frac{1}{n} \sum_{i=1}^n f(x_i)$$

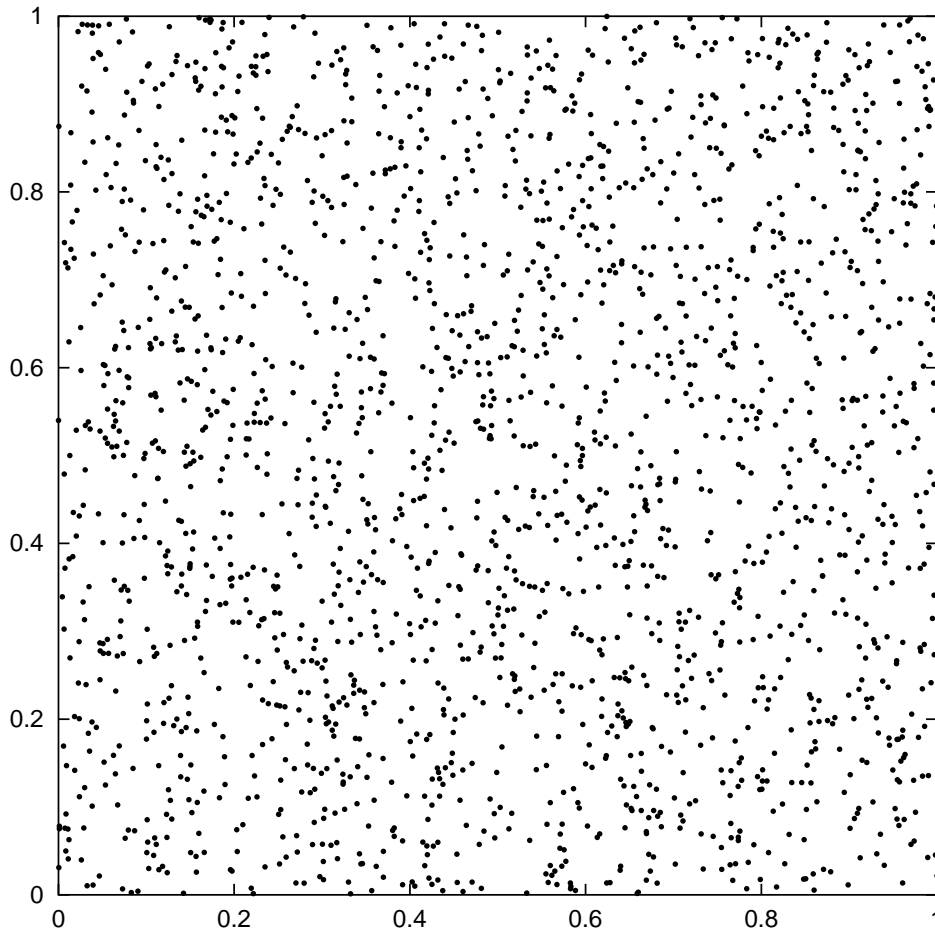
with x_i random samples uniformly distributed in C_s .

- $|If - Q_n f| \approx \frac{\sigma(f)}{\sqrt{n}} = \sqrt{\frac{\text{Var}(f)}{n}} = \mathcal{O}(n^{-1/2})$
- Independent of dimension s
- $\sigma(f)$ behaves well for a huge class of integrands
- We can even estimate the accuracy:

$$|If - Q_n f| \approx \sqrt{\frac{\text{Var}(f)}{n}} \approx \sqrt{\frac{\sum f^2(x_i) - \frac{1}{n} (\sum f(x_i))^2}{n(n-1)}}$$

- \Rightarrow MC integration is a pretty foolproof way to estimate an integral

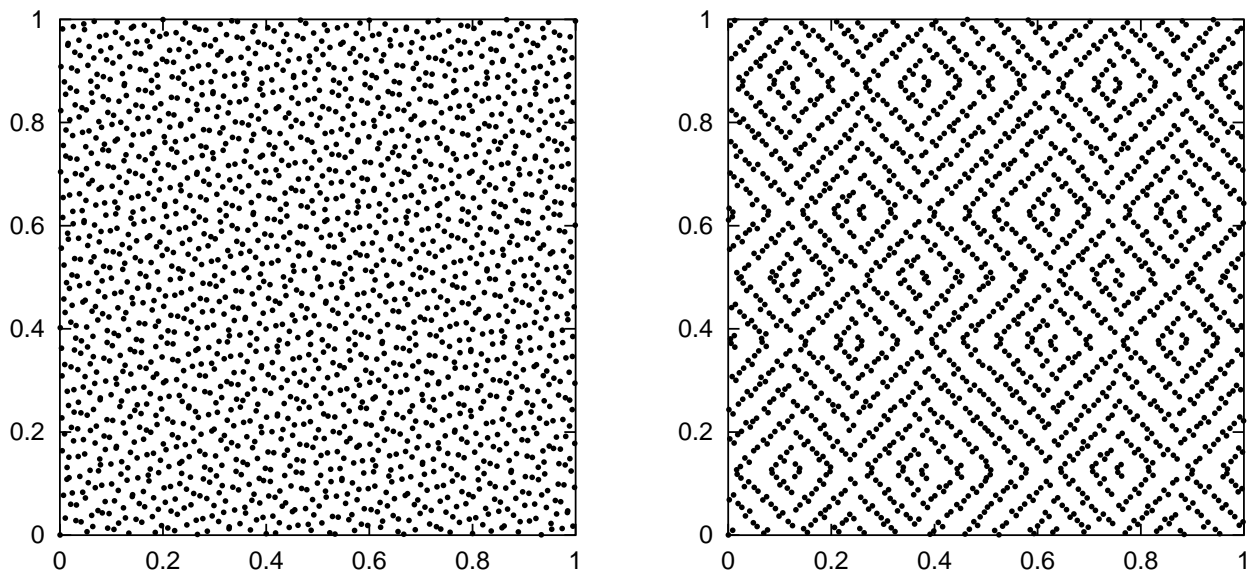
Can we do better?



- Random points are evenly distributed in any dimension
- However, random clusters and gaps appear
- Are there high-dimensional, evenly distributed, but regular point sets?

Quasi-Monte Carlo

- Instead of drawing random samples, use low discrepancy point-sets like (t, m, s) -nets!



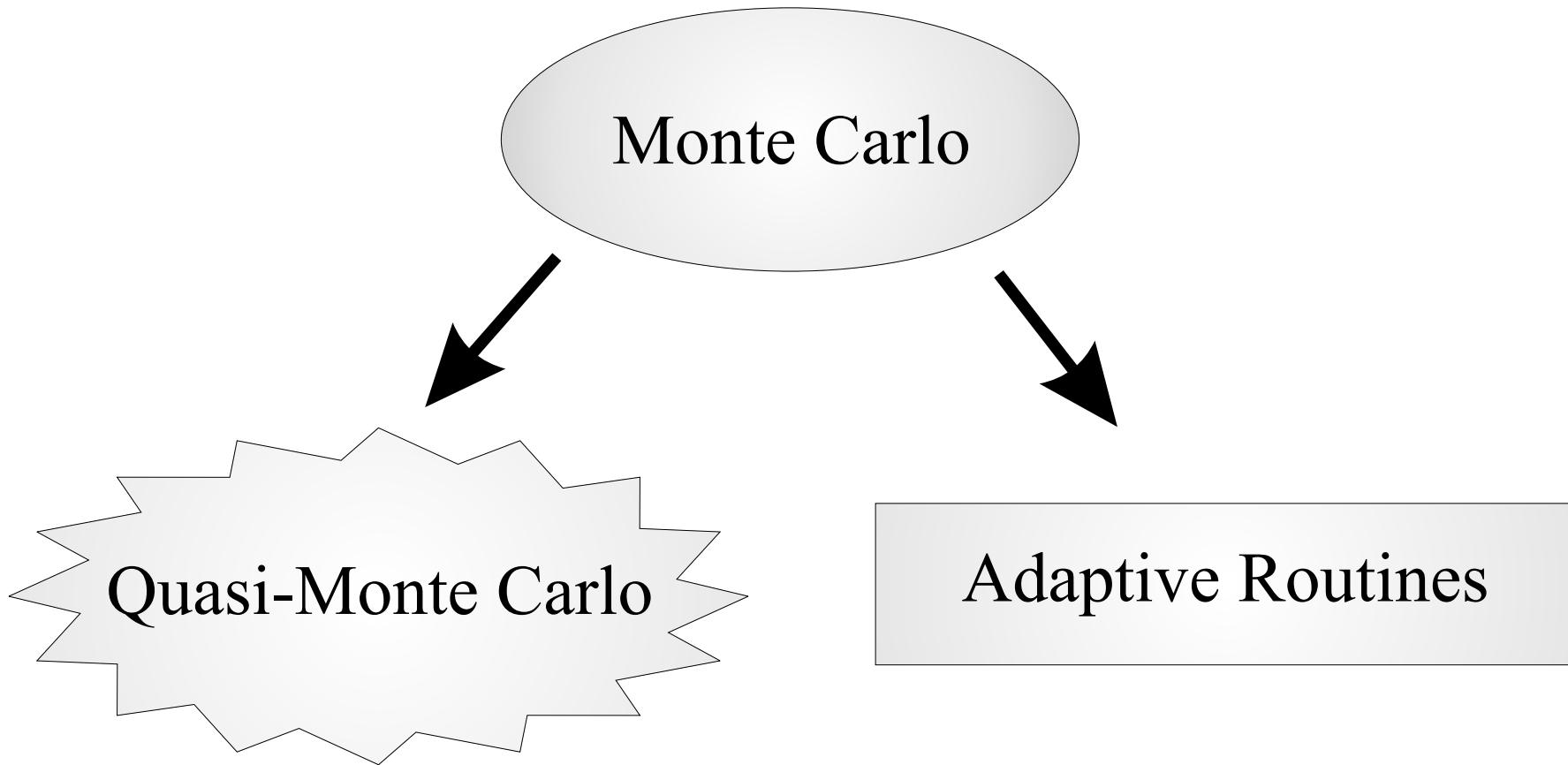
The first 2048 points from the Sobol sequence
 x_1x_3 -projection (left), $x_{37}x_{40}$ -projection (right)

Performance of Quasi-Monte Carlo

- Koksma-Hlawka inequality:

$$|\mathbb{I}f - Q_n f| \leq V(f) \cdot D_n^* \leq c \frac{\log^s n}{n}$$

- Only an upper bound, no estimator
 - $V(f) = \infty$ even for simple integrands
 - No general method for estimating $V(f)$
 - $\log^s n$ is huge for affordable n
- However, it works quite well in practice:
 $|\mathbb{I}f - Q_n f| \approx \mathcal{O}(n^{-1})$ is usually obtained!



Adaptive Integration

Algorithm 1 Adaptive Integration

Put C_s into region collection

while estimated error too large **do**

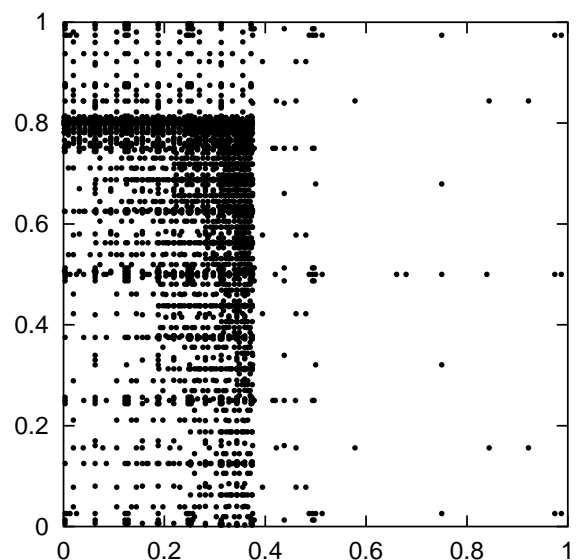
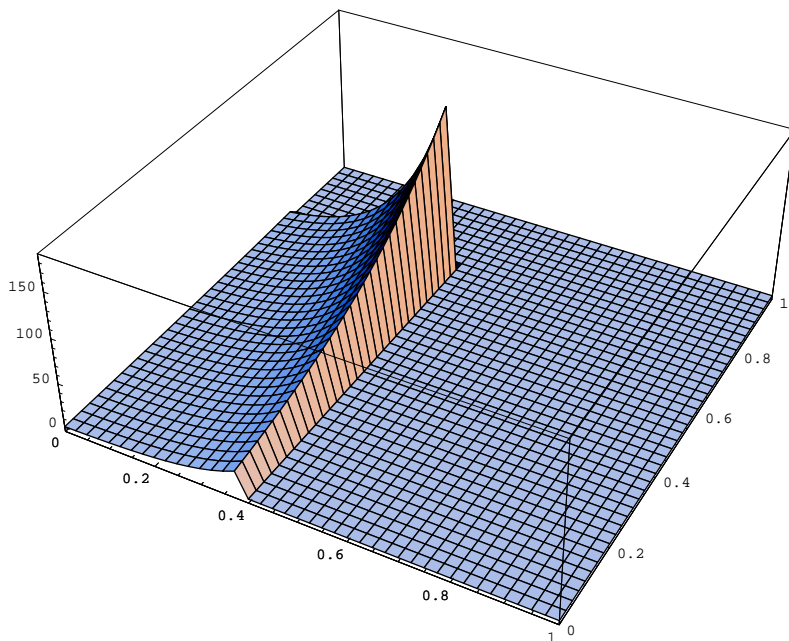
 Choose subregion with large error

 Split region

 Apply basic rule

 Store new regions in region collection

end while



Stratified Sampling

Taking $n/2$ samples from two halves of C_s is always better than sampling C_s with n points!

$$\tilde{Q}_n f = \frac{1}{2} (Q_{n/2} f_\alpha + Q_{n/2} f_\beta)$$

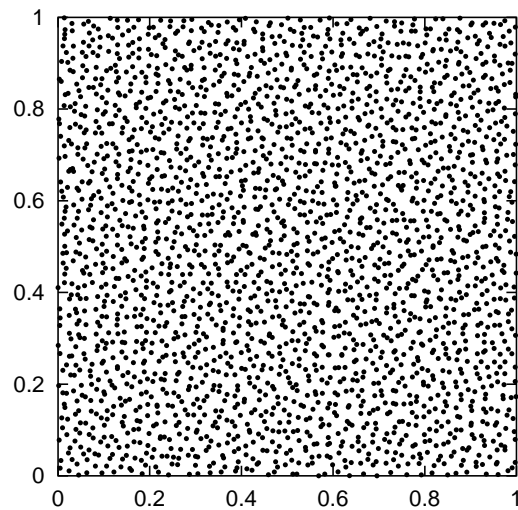
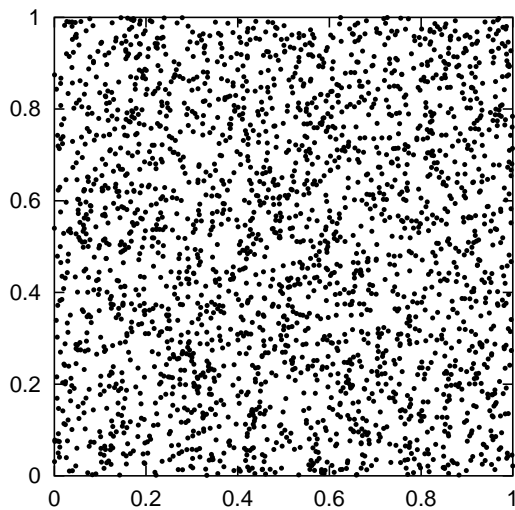
with f_α and f_β denoting f restricted to the left and right subcube.

Variance of this estimator:

$$\begin{aligned} \text{Var}(\tilde{Q}_n f) &= \frac{1}{4} \left(\text{Var}(Q_{n/2} f_\alpha) + \text{Var}(Q_{n/2} f_\beta) \right) \\ &\approx \frac{1}{4} \left(\frac{\text{Var}(f_\alpha)}{n/2} + \frac{\text{Var}(f_\beta)}{n/2} \right) \\ &= \frac{1}{2n} \left(\text{Var}(f_\alpha) + \text{Var}(f_\beta) \right) \\ &= \frac{1}{n} \cdot \frac{\text{Var}(f_\alpha) + \text{Var}(f_\beta)}{2} \\ &\leq \frac{1}{n} \cdot \text{Var}(f) = \text{Var}(Q_n f) \end{aligned}$$

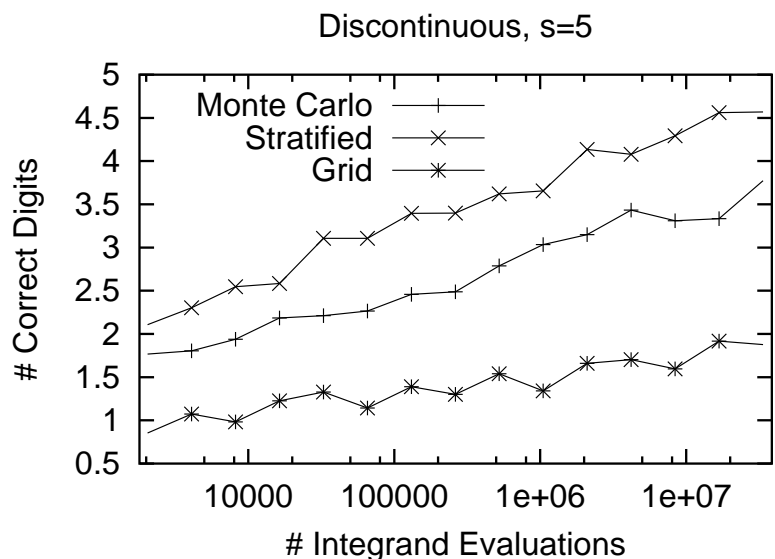
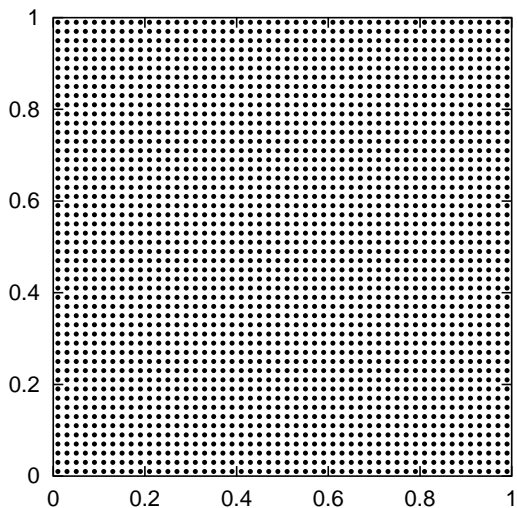
Recursive Stratified Sampling

Stratification can be done recursively, leading to n subcubes with one random point in each of them.



This comes close to a grid.

However, randomization performs much better!



MISER – Adaptive Stratification

Stratification improves performance whenever

$$\sigma(f_\alpha) \neq \sigma(f_\beta).$$

The optimal performance can be achieved by allocating points such that

$$n_\alpha/n_\beta = \sigma(f_\alpha)/\sigma(f_\beta).$$

This lead directly to the following adaptive algorithm:

Algorithm 2 MISER

- 1: Allocate points for presampling
 - 2: Estimate $\sigma_{\alpha i}$ and $\sigma_{\beta i}$ for all $i = 1, \dots, s$ halves
 - 3: Choose split dimension
 - 4: Assign point budgets N_α and N_β
 - 5: Apply MISER to both subcubes
 - 6: Calculate final estimate
-

Importance Sampling

- Integration error depends on $\text{Var}(f)$
- What if
 - We have positive-valued function p with

$$\int_{C_s} p(\mathbf{x}) d\mathbf{x} = 1,$$

i. e. p is a probability density function

- p mimics f such that $p \simeq |f|$

- Then
 - f/p has a very low variance
 -

$$\int_{C_s} f(\mathbf{x}) d\mathbf{x} = \int_{C_s} \frac{f(\mathbf{x})}{p(\mathbf{x})} dP(\mathbf{x}),$$

i. e. the sample mean of f/p with density p equals sample mean of f with density 1.

Recipe:

Find a pdf p with

- $p \simeq |f|$
- We can generate p -distributed random numbers

Adaptive Importance Sampling

Algorithm 3 Adaptive Importance Sampling

Start with $p \equiv 1/\text{vol } C_s$

for $i = 1, \dots, m$ **do**

 Sample f/p to refine p

end for

Use remaining points to sample f/p with density p

Algorithms differ by the available functions p and by the way they are estimated.

VEGAS

VEGAS uses a product of piecewise constant, one-dimensional functions.

Control Variates

Break f into two parts φ and $(f - \varphi)$ such that

- I_φ can be calculated analytically
- $Var(f - \varphi)$ is small

-

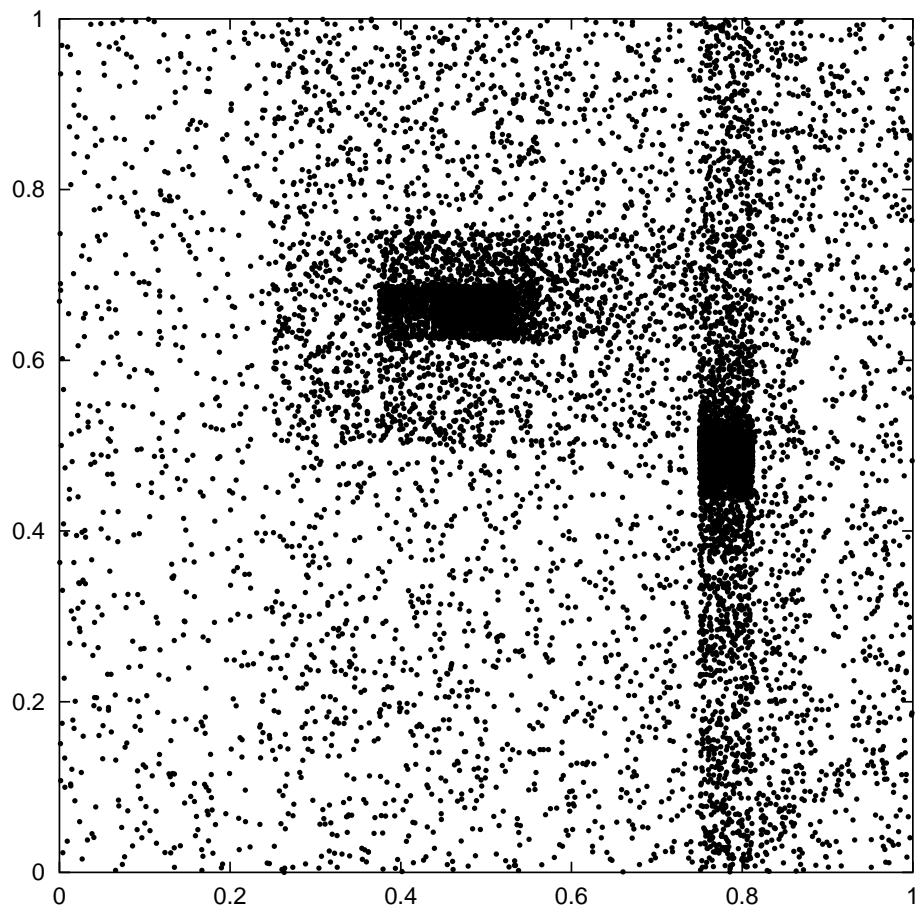
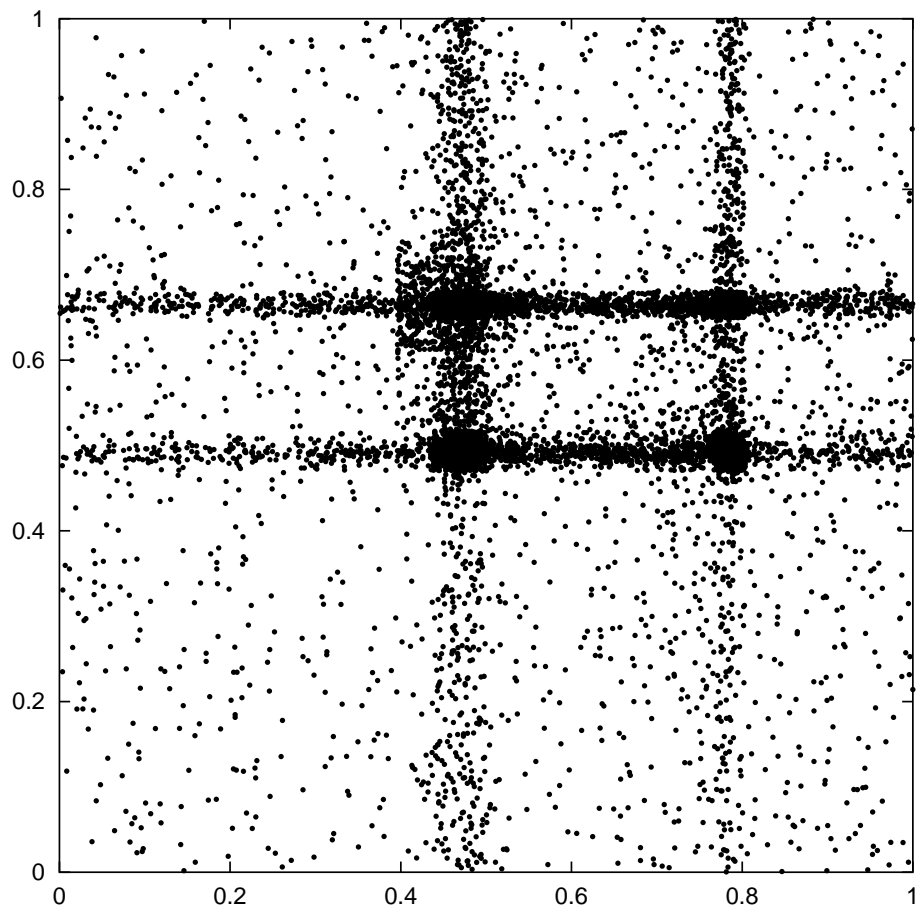
$$\begin{aligned}Q_n f &= I_\varphi + \frac{1}{n} \sum_{i=1}^n (f - \varphi)(\mathbf{x}_i) \\&= I_\varphi + \frac{1}{n} \sum_{i=1}^n f(\mathbf{x}_i) + \frac{1}{n} \sum_{i=1}^n \varphi(\mathbf{x}_i) \\&= I_\varphi + \tilde{f} + \tilde{\varphi}\end{aligned}$$

-

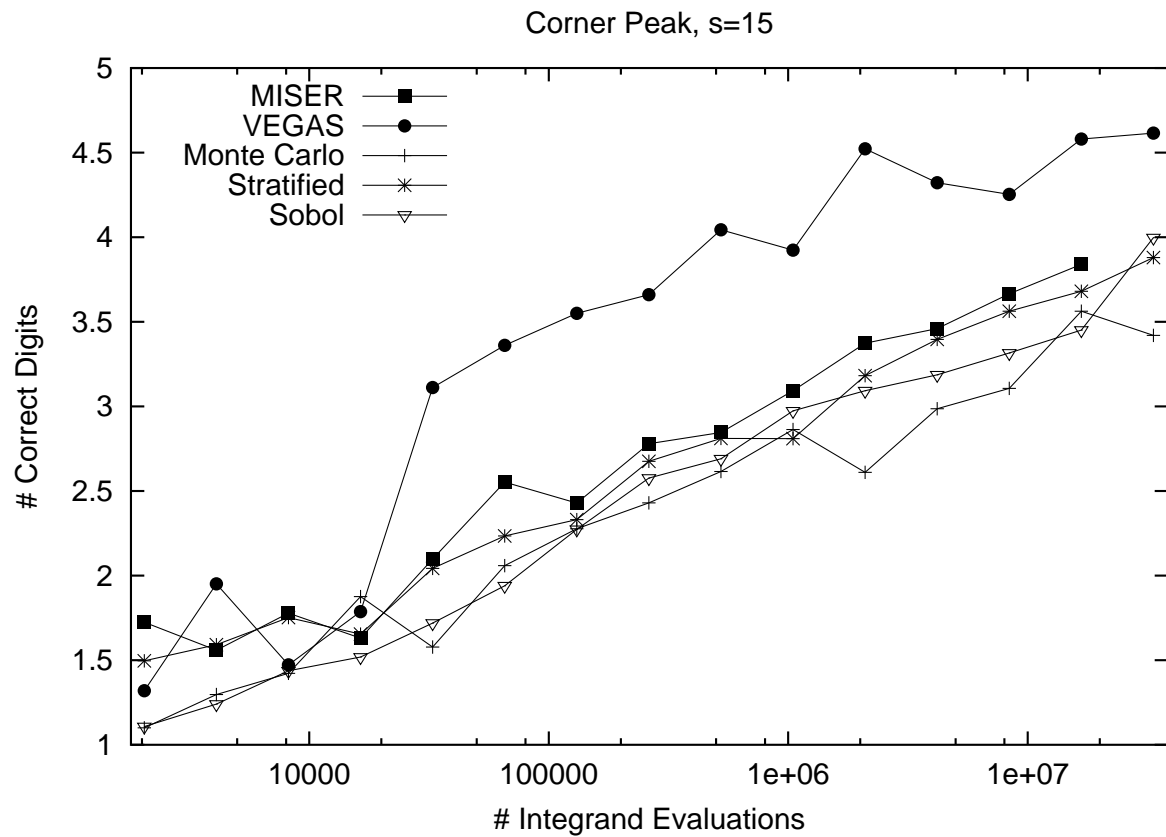
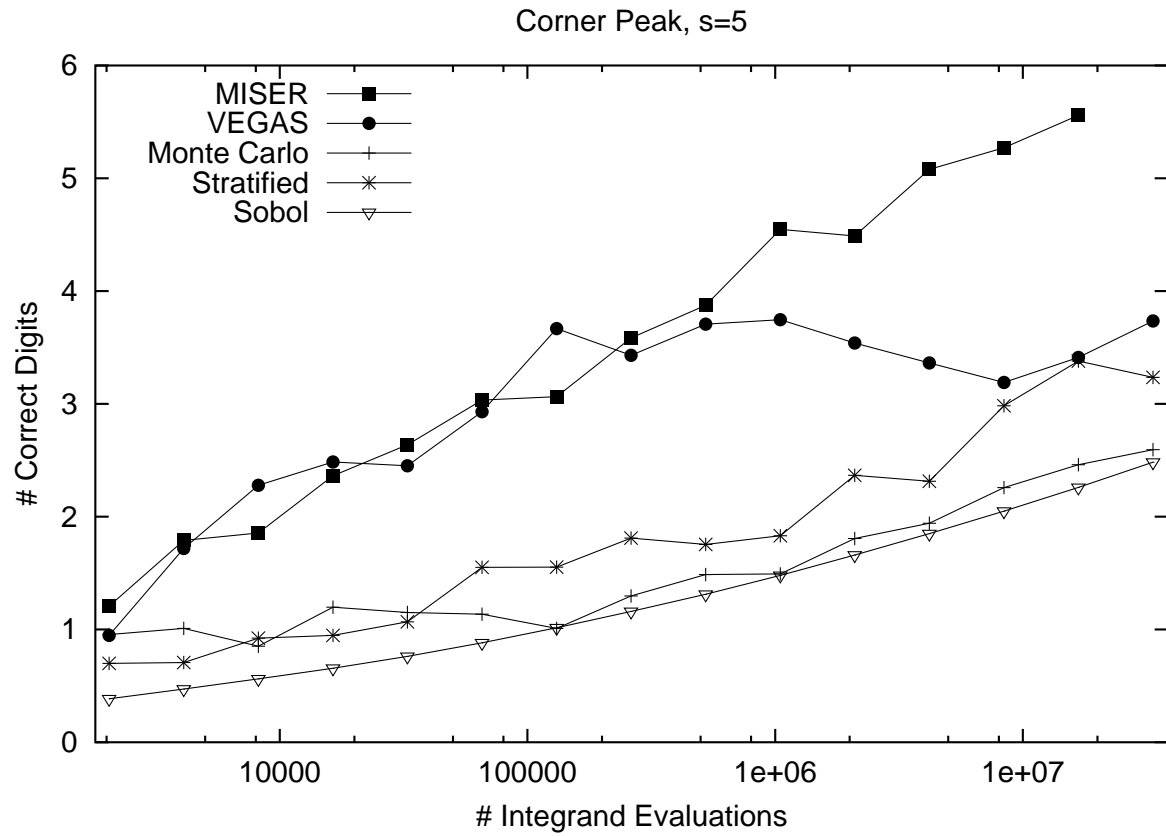
$$Var(Q_n f) = Var(\tilde{f}) + Var(\tilde{\varphi}) - 2Cov(\tilde{f}, \tilde{\varphi})$$

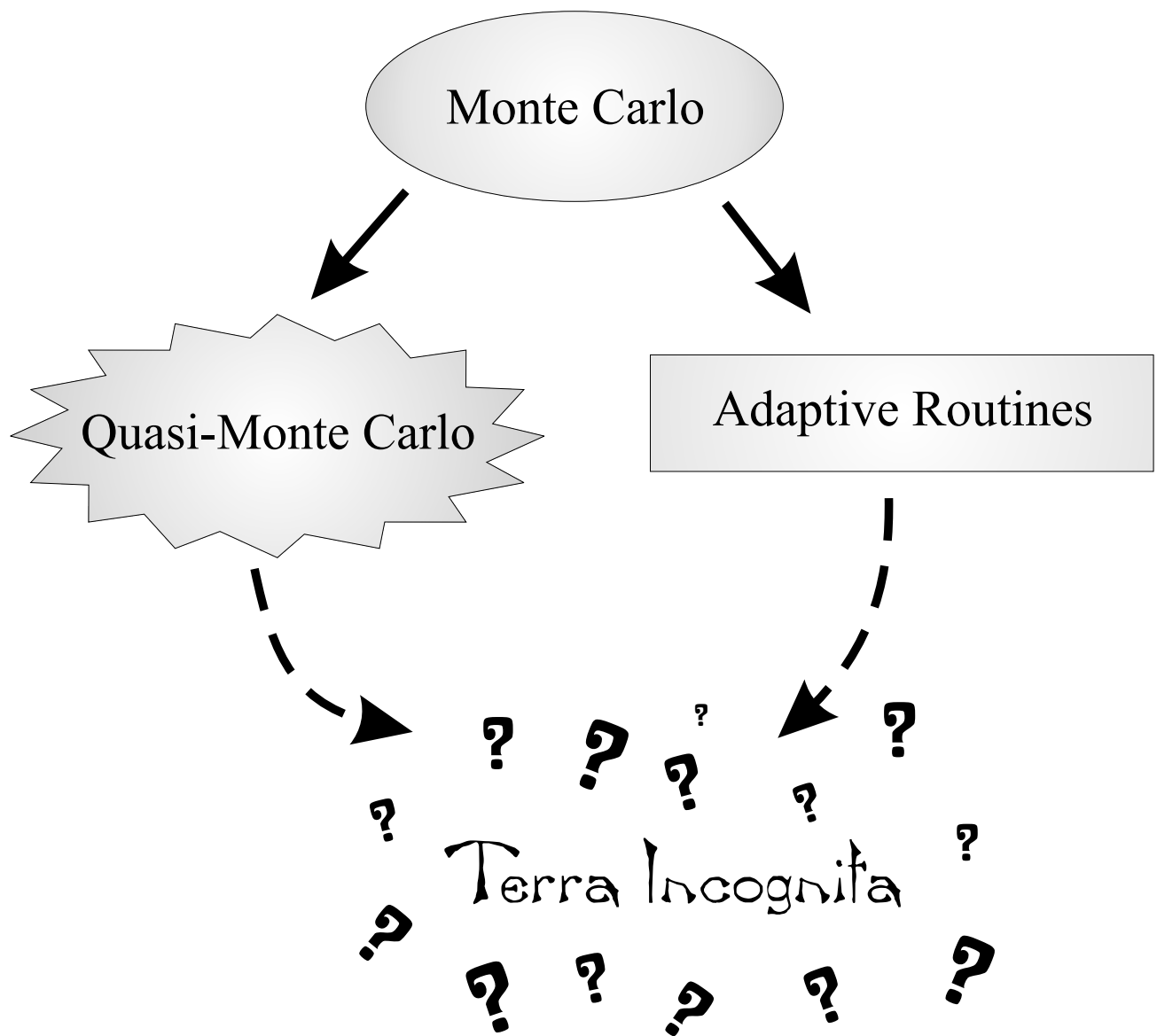
How can be find φ ?

- “Parallel Simulation”
- Adaptive?



Results





Can we extend these results to QMC?

- Key Concept “Variance Reduction”
 - $Var(f)$ can be estimated easily. However, there is no direct correlation between $Var(f)$ and the integration error.
 - Knowing $V(f)$ would give an upper bound. However, it can neither be estimated nor is the inequality sharp.
 - There are empirical results suggesting that $|Q_n f - If| \approx \frac{Var(f)}{n}$ for many integrands
 - Integration error can be estimated using randomized QMC (e. g.: Owen Scrambling)
- Generating arbitrary distributions is possible, at least if an explicit transformation function is available.
- Applying two nets of size $n/2$ to two halves of C_s definitely *decreases* performance
- QMC integration has a high rate of convergence by itself. Therefore, improving on it will be harder.